

Asialog : pemindaian jurnal perusahaan India : perbandingan lintasan input dan lintasan koreksi = Asialog : scanning of journals india company : comparison of tracks input and tracks correction / Elfisa

Elfisa, author

Deskripsi Lengkap: <https://lib.ui.ac.id/detail?id=20364724&lokasi=lokal>

Abstrak

ABSTRACT

Penelitian yang disajikan dalam laporan ini dilakukan di Laboratorium IRISA – UBS (Institut de Recherche en Informatique et Systèmes Aléatoires – Université de Bretagne Sud) dengan judul “ Asialog : Pemindaian Jurnal Perusahaan India (Perbandingan Lintasan Input dan Lintasan Koreksi)” di bawah arahan Jeanne Villaneau.

Tujuan dari proyek ini adalah membedakan lintasan input dan lintasan koreksi kapal.

Sebelumnya pencatatan perjalanan kapal dicatat secara manual. Titik point pencatatan diperoleh dari pangakalan data (database). Lintasan koreksi diperoleh dari pencarian titik kesalahan berdasarkan perbedaan jarak. Untuk mendeteksi titik kesalahan ditentukan jarak tiap titik point marker.

Dalam proyek ini, menampilkan peta posisi lintasan kapal dengan lintasan input dan lintasan koreksi dengan keterangan titik Longitude dan Latitude. Peta disini menggunakan Openstreetmap berbasis Linux.

<hr>

ABSTRACT

The research presented in this report was carried out in the Laboratory IRISA-UBS (Institute for Research in Computer Science and Random Systems - University of South Brittany) on the subject Asialog: Scanning of Journals India Company (Comparison of Tracks Input and Tracks Correction).

The aim of my work is distinguished path of travel and entry path fixes boat. The purpose of the trip is correct enter road before boat ride on the old manual card. Input path is obtained from the point of the database. While the path is corrected obtained by finding the point of error based on the distance. To detect the error point is determined the distance between the point at any time based on changes that have been determined.

In this project, I will display the route map entry and correct with respect to the longitude and latitude points. To view the map, I use OpenStreetMap program under Linux platform.