

Advanced bimanual manipulation: results from the DEXMART project

Deskripsi Lengkap: <https://lib.ui.ac.id/detail?id=20397727&lokasi=lokal>

Abstrak

[This book reports on the DEXMART research project, which sought to fill the gap between the use of dexterous and autonomous dual-hand manipulative robots in industrial environments and the use of future robots in everyday human and unstructured environments. , This book reports on the DEXMART research project, which sought to fill the gap between the use of dexterous and autonomous dual-hand manipulative robots in industrial environments and the use of future robots in everyday human and unstructured environments.]