



LAMPIRAN 1

Metode Newton-Raphson

Misalkan θ adalah vektor dari 2 buah parameter yaitu β dan γ .

θ dapat dituliskan sebagai berikut $\theta = \begin{bmatrix} \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \\ \gamma_1 \\ \gamma_2 \\ \vdots \\ \gamma_{M-1} \end{bmatrix}$.

$L^*(\theta)$ adalah fungsi *log likelihood* dari vektor θ , sedangkan $f'(\theta)$ merupakan vektor turunan parsial pertama dari $L^*(\theta)$ dapat ditulis sebagai berikut :

$$f'(\theta) = \begin{bmatrix} \frac{\partial L^*(\theta)}{\partial \beta_0} \\ \frac{\partial L^*(\theta)}{\partial \beta_1} \\ \frac{\partial L^*(\theta)}{\partial \beta_2} \\ \vdots \\ \frac{\partial L^*(\theta)}{\partial \beta_p} \\ \frac{\partial L^*(\theta)}{\partial \gamma_1} \\ \vdots \\ \frac{\partial L^*(\theta)}{\partial \gamma_{M-1}} \end{bmatrix}$$

dan $\mathbf{H}(\boldsymbol{\theta})$ adalah matriks turunan parsial kedua dari $L^*(\boldsymbol{\theta})$ yaitu :

$$\mathbf{H}(\boldsymbol{\theta}) = \begin{bmatrix} \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_0} & \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_1} & \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_2} & \dots & \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_p} & \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \gamma_1} & \dots & \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \gamma_{M-1}} \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \beta_0} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \beta_0} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \beta_0} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \beta_0} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \beta_0} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_{M-1} \beta_0} \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \beta_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \beta_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \beta_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \beta_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \beta_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_{M-1} \beta_1} \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \beta_2} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \beta_2} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \beta_2} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \beta_2} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \beta_2} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_{M-1} \beta_2} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \beta_p} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \beta_p} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_{M-1} \beta_p} \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \gamma_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \gamma_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \gamma_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_{M-1} \gamma_1} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \gamma_{M-1}} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \gamma_{M-1}} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \gamma_{M-1}} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \gamma_{M-1}} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \gamma_{M-1}} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_{M-1} \gamma_{M-1}} \end{bmatrix}$$

Dengan menggunakan metode Newton Raphson akan dicari taksiran dari $\boldsymbol{\theta}$ yang merupakan penyelesaian dari $\mathbf{f}'(\boldsymbol{\theta}) = \mathbf{0}$. Jika diberikan taksiran awal dari $\boldsymbol{\theta}$ yaitu $\hat{\boldsymbol{\theta}}^{(0)}$, maka dapat diperoleh pendekatan deret Taylor orde pertama dari vektor $\mathbf{f}'(\boldsymbol{\theta})$ di sekitar $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(0)}$ yaitu :

$$\begin{aligned}
\mathbf{f}'(\boldsymbol{\theta}) &\approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) + \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_0} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} (\beta_0 - \hat{\beta}_0^{(0)}) + \dots + \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_p} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} (\beta_p - \hat{\beta}_p^{(0)}) + \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \gamma_1} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} (\gamma_1 - \hat{\gamma}_1^{(0)}) + \dots + \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \gamma_{M-1}} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} (\gamma_{M-1} - \hat{\gamma}_{M-1}^{(0)}) \\
&\approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) + \begin{bmatrix} \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_0} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} & \dots & \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \beta_p} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} & \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \gamma_1} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} & \dots & \left. \frac{\partial \mathbf{f}'(\boldsymbol{\theta})}{\partial \gamma_{M-1}} \right|_{\boldsymbol{\theta}=\hat{\boldsymbol{\theta}}^{(0)}} \end{bmatrix} \begin{bmatrix} (\beta_0 - \hat{\beta}_0^{(0)}) \\ \vdots \\ (\beta_p - \hat{\beta}_p^{(0)}) \\ (\gamma_1 - \hat{\gamma}_1^{(0)}) \\ \vdots \\ (\gamma_{M-1} - \hat{\gamma}_{M-1}^{(0)}) \end{bmatrix} \\
&\approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) + \begin{bmatrix} \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_0} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_2} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \gamma_{M-1}} \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \beta_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \beta_2} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \gamma_{M-1}} \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_2} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \beta_2} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \partial \beta_2} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \partial \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \partial \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \partial \gamma_{M-1}} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \partial \beta_p} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \partial \beta_p} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \partial \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \partial \gamma_{M-1}} \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \gamma_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \gamma_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \partial \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \partial \gamma_1} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \partial \gamma_1} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \partial \gamma_{M-1}} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \partial \gamma_{M-1}} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \partial \gamma_{M-1}} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_2 \partial \gamma_{M-1}} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \partial \gamma_{M-1}} & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_1 \partial \gamma_{M-1}} & \dots & \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \gamma_{M-1} \partial \gamma_{M-1}} \end{bmatrix} (\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)}) \\
&\approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) + \begin{bmatrix} H_{\beta_0 \beta_0}(\boldsymbol{\theta}) & \dots & H_{\beta_0 \beta_p}(\boldsymbol{\theta}) & H_{\beta_0 \gamma_1}(\boldsymbol{\theta}) & \dots & H_{\beta_0 \gamma_{M-1}}(\boldsymbol{\theta}) \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ H_{\beta_0 \beta_p}(\boldsymbol{\theta}) & \dots & H_{\beta_p \beta_p}(\boldsymbol{\theta}) & H_{\beta_p \gamma_1}(\boldsymbol{\theta}) & \dots & H_{\beta_p \gamma_{M-1}}(\boldsymbol{\theta}) \\ H_{\beta_0 \gamma_1}(\boldsymbol{\theta}) & \dots & H_{\beta_p \gamma_1}(\boldsymbol{\theta}) & H_{\gamma_1 \gamma_1}(\boldsymbol{\theta}) & \dots & H_{\gamma_1 \gamma_{M-1}}(\boldsymbol{\theta}) \\ \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ H_{\beta_0 \gamma_{M-1}}(\boldsymbol{\theta}) & \dots & H_{\beta_p \gamma_{M-1}}(\boldsymbol{\theta}) & H_{\gamma_1 \gamma_{M-1}}(\boldsymbol{\theta}) & \dots & H_{\gamma_{M-1} \gamma_{M-1}}(\boldsymbol{\theta}) \end{bmatrix} (\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)})
\end{aligned}$$

Atau dapat ditulis juga

$$\mathbf{f}'(\boldsymbol{\theta}) \approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) + \mathbf{H}(\hat{\boldsymbol{\theta}}^{(0)}) (\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)})$$

dengan :

$\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)})$ adalah vektor turunan parsial pertama dari $L^*(\boldsymbol{\theta})$ dihitung pada $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(0)}$.

$\mathbf{H}(\hat{\boldsymbol{\theta}}^{(0)})$ adalah matriks turunan parsial kedua dari $L^*(\boldsymbol{\theta})$ dihitung pada $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(0)}$.

Karena ingin mencari penyelesaian dari $\mathbf{f}'(\boldsymbol{\theta}) = \mathbf{0}$ maka :

$$\mathbf{0} = \mathbf{f}'(\boldsymbol{\theta}) \approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) + \mathbf{H}(\hat{\boldsymbol{\theta}}^{(0)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)})$$

$$\mathbf{0} = \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) + \mathbf{H}(\hat{\boldsymbol{\theta}}^{(0)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)})$$

$$-\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) = \mathbf{H}(\hat{\boldsymbol{\theta}}^{(0)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)})$$

Jika matriks $\mathbf{H}(\hat{\boldsymbol{\theta}}^{(0)})$ tidak singular maka :

$$\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(0)}) \cdot -\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}) = \mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(0)})\mathbf{H}(\hat{\boldsymbol{\theta}}^{(0)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)})$$

$$-(\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(0)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)})) = \mathbf{I}(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)})$$

$$-(\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(0)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)})) = \boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(0)}$$

$$\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(0)} - (\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(0)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}))$$

Nilai $\boldsymbol{\theta}$ menjadi taksiran baru yang kemudian dinotasikan dengan $\hat{\boldsymbol{\theta}}^{(1)}$:

$$\hat{\boldsymbol{\theta}}^{(1)} = \hat{\boldsymbol{\theta}}^{(0)} - (\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(0)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(0)}))$$

Jika $\hat{\boldsymbol{\theta}}^{(1)} \approx \hat{\boldsymbol{\theta}}^{(0)}$ (misalkan $\|\hat{\boldsymbol{\theta}}^{(m+1)} - \hat{\boldsymbol{\theta}}^{(m)}\| < 10^{-5}$), maka hentikan proses iterasi dan

kemudian ambil $\hat{\boldsymbol{\theta}}^{(1)}$ sebagai taksiran dari $\hat{\boldsymbol{\theta}}$. Apabila tidak maka lanjutkan

iterasi. Jika diberikan taksiran $\hat{\boldsymbol{\theta}}^{(1)}$ maka dapat diperoleh pendekatan deret

Taylor orde pertama dari vektor $\mathbf{f}'(\boldsymbol{\theta})$ sekitar $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(1)}$, yaitu :

$$\mathbf{f}'(\boldsymbol{\theta}) \approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)}) + \mathbf{H}(\hat{\boldsymbol{\theta}}^{(1)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(1)})$$

dengan :

$\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)})$ adalah vektor turunan parsial pertama dari $L^*(\boldsymbol{\theta})$ dihitung pada $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(1)}$.

$\mathbf{H}(\hat{\boldsymbol{\theta}}^{(1)})$ adalah matriks turunan parsial kedua dari $L^*(\boldsymbol{\theta})$ dihitung pada $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(1)}$.

Dengan menyelesaikan :

$$\mathbf{0} = \mathbf{f}'(\boldsymbol{\theta}) \approx \mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)}) + \mathbf{H}(\hat{\boldsymbol{\theta}}^{(1)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(1)})$$

diperoleh :

$$-\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)}) = \mathbf{H}(\hat{\boldsymbol{\theta}}^{(1)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(1)})$$

Jika matriks $\mathbf{H}(\hat{\boldsymbol{\theta}}^{(1)})$ tidak singular maka :

$$\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(1)}) \cdot -\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)}) = \mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(1)})\mathbf{H}(\hat{\boldsymbol{\theta}}^{(1)})(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(1)})$$

$$-\left(\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(1)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)})\right) = \mathbf{I}(\boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(1)})$$

$$-\left(\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(1)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)})\right) = \boldsymbol{\theta} - \hat{\boldsymbol{\theta}}^{(1)}$$

$$\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(1)} - \left(\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(1)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)})\right)$$

Nilai $\boldsymbol{\theta}$ menjadi taksiran baru yang kemudian dinotasikan dengan $\hat{\boldsymbol{\theta}}^{(2)}$:

$$\hat{\boldsymbol{\theta}}^{(2)} = \hat{\boldsymbol{\theta}}^{(1)} - \left(\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(1)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(1)})\right)$$

Jika $\hat{\boldsymbol{\theta}}^{(2)} \approx \hat{\boldsymbol{\theta}}^{(1)}$ (misalkan $\|\hat{\boldsymbol{\theta}}^{(m+1)} - \hat{\boldsymbol{\theta}}^{(m)}\| < 10^{-5}$), maka hentikan proses iterasi dan kemudian ambil $\hat{\boldsymbol{\theta}}^{(2)}$ sebagai taksiran dari $\hat{\boldsymbol{\theta}}$. Apabila tidak maka lanjutkan iterasi.

Dengan mengulang langkah yang sama dapat diperoleh taksiran $\hat{\boldsymbol{\theta}}^{(3)}$, $\hat{\boldsymbol{\theta}}^{(4)}$, dan seterusnya. Secara umum dapat ditentukan taksiran dari $\boldsymbol{\theta}$ pada iterasi ke- $m+1$, yaitu $\hat{\boldsymbol{\theta}}^{(m+1)}$, secara iteratif menggunakan formula :

$$\hat{\boldsymbol{\theta}}^{(m+1)} = \hat{\boldsymbol{\theta}}^{(m)} - \left(\mathbf{H}^{-1}(\hat{\boldsymbol{\theta}}^{(m)})\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(m)})\right), m=0,1,2,3,\dots$$

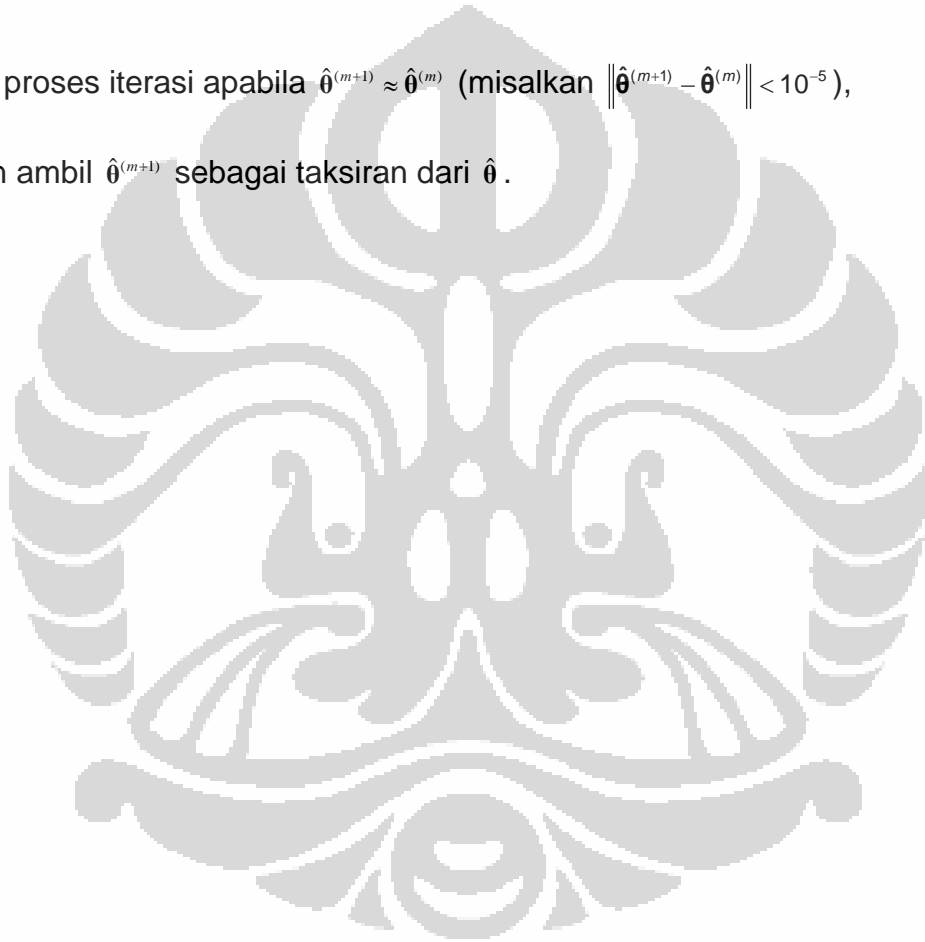
dengan :

$\mathbf{f}'(\hat{\boldsymbol{\theta}}^{(m)})$ adalah vektor turunan parsial pertama dari $L^*(\boldsymbol{\theta})$ dihitung pada $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(m)}$.

$\mathbf{H}(\hat{\boldsymbol{\theta}}^{(m)})$ adalah matriks turunan parsial kedua dari $L^*(\boldsymbol{\theta})$ dihitung pada $\boldsymbol{\theta} = \hat{\boldsymbol{\theta}}^{(m)}$.

Hentikan proses iterasi apabila $\hat{\boldsymbol{\theta}}^{(m+1)} \approx \hat{\boldsymbol{\theta}}^{(m)}$ (misalkan $\|\hat{\boldsymbol{\theta}}^{(m+1)} - \hat{\boldsymbol{\theta}}^{(m)}\| < 10^{-5}$),

kemudian ambil $\hat{\boldsymbol{\theta}}^{(m+1)}$ sebagai taksiran dari $\hat{\boldsymbol{\theta}}$.



LAMPIRAN 2

Mencari Matriks Variansi – Kovariansi Dari $\hat{\beta}$

Untuk Model Regresi Linear

Akan dicari matriks variansi – kovariansi dari $\hat{\beta}$ yang didefinisikan sebagai berikut :

$$V(\hat{\beta}) = E\left(\left(\hat{\beta} - E(\hat{\beta})\right)\left(\hat{\beta} - E(\hat{\beta})\right)^T\right). \quad (1)$$

Untuk tujuan tersebut mula-mula dimisalkan terdapat n observasi yang saling bebas dan Y_j merupakan variabel *dependent* untuk observasi ke- j ; $j = 1, 2, \dots, n$. Misalkan $f(y_j | \mathbf{x}_j; \beta)$ adalah pdf bersyarat dari Y_j diberikan nilai \mathbf{x}_j , dimana $\mathbf{x}_j = (x_{1j}, x_{2j}, \dots, x_{pj})$ adalah vektor dari nilai variabel penjelas untuk observasi ke- j ; $j = 1, 2, \dots, n$, dan $\beta = (\beta_0, \beta_1, \beta_2, \dots, \beta_p)^T$.

Fungsi log-likelihood dapat dituliskan sebagai berikut :

$$\begin{aligned} L^*(\beta) &= \log \prod_{j=1}^n f(y_j | \mathbf{x}_j, \beta_0, \beta_1, \dots, \beta_p) \\ &= \sum_{j=1}^n \log f(y_j | \mathbf{x}_j, \beta_0, \beta_1, \dots, \beta_p) \\ &= \sum_{j=1}^n \log f(y_j | \mathbf{x}_j, \beta) \end{aligned} \quad (2)$$

Turunan parsial pertama dari $L^*(\boldsymbol{\beta})$ terhadap $\boldsymbol{\beta}$ dinyatakan oleh :

$$\begin{aligned} f'_u(\boldsymbol{\beta}) &= \frac{\partial L^*(\boldsymbol{\beta})}{\partial \beta_u} \\ &= \frac{\partial}{\partial \beta_u} \sum_{j=1}^n \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \\ &= \sum_{j=1}^n \frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \quad ; u = 0, 1, 2, \dots, p \end{aligned} \quad (3)$$

Misalkan $\mathbf{f}'(\boldsymbol{\beta})$ adalah vektor dengan elemen $f'_0(\boldsymbol{\beta}), f'_1(\boldsymbol{\beta}), \dots, f'_p(\boldsymbol{\beta})$, yaitu :

$$\mathbf{f}'(\boldsymbol{\beta}) = \begin{bmatrix} f'_0(\boldsymbol{\beta}) \\ f'_1(\boldsymbol{\beta}) \\ \vdots \\ f'_p(\boldsymbol{\beta}) \end{bmatrix} \text{ dan misalkan } L^*(\boldsymbol{\beta}) \text{ memiliki maksimum yang unik pada } \hat{\boldsymbol{\beta}};$$

$$\hat{\boldsymbol{\beta}} = (\hat{\beta}_0, \hat{\beta}_1, \dots, \hat{\beta}_p)^T.$$

Dengan menggunakan pendekatan deret Taylor orde pertama dari matriks

$\mathbf{f}'(\boldsymbol{\beta})$ di sekitar $\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}$ diperoleh :

$$\begin{aligned} \mathbf{f}'(\boldsymbol{\beta}) &\approx \mathbf{f}'(\hat{\boldsymbol{\beta}}) + \left. \frac{\partial \mathbf{f}'(\boldsymbol{\beta})}{\partial \beta_0} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} (\beta_0 - \hat{\beta}_0) + \left. \frac{\partial \mathbf{f}'(\boldsymbol{\beta})}{\partial \beta_1} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} (\beta_1 - \hat{\beta}_1) + \dots + \left. \frac{\partial \mathbf{f}'(\boldsymbol{\beta})}{\partial \beta_p} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} (\beta_p - \hat{\beta}_p) \\ &\approx \mathbf{f}'(\hat{\boldsymbol{\beta}}) + \begin{bmatrix} \left. \frac{\partial \mathbf{f}'(\boldsymbol{\beta})}{\partial \beta_0} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \left. \frac{\partial \mathbf{f}'(\boldsymbol{\beta})}{\partial \beta_1} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \dots & \left. \frac{\partial \mathbf{f}'(\boldsymbol{\beta})}{\partial \beta_p} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} \end{bmatrix} \begin{bmatrix} \beta_0 - \hat{\beta}_0 \\ \beta_1 - \hat{\beta}_1 \\ \vdots \\ \beta_p - \hat{\beta}_p \end{bmatrix} \\ &\approx \mathbf{f}'(\hat{\boldsymbol{\beta}}) + \begin{bmatrix} \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \beta_0} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \beta_0} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \dots & \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \beta_0} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} \\ \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \beta_1} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \beta_1} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \dots & \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \beta_1} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} \\ \vdots & \vdots & \ddots & \vdots \\ \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_0 \beta_p} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_1 \beta_p} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} & \dots & \left. \frac{\partial^2 L^*(\boldsymbol{\theta})}{\partial \beta_p \beta_p} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} \end{bmatrix} \begin{bmatrix} \beta_0 - \hat{\beta}_0 \\ \beta_1 - \hat{\beta}_1 \\ \vdots \\ \beta_p - \hat{\beta}_p \end{bmatrix} \end{aligned}$$

atau

$$\mathbf{f}'(\boldsymbol{\beta}) \approx \mathbf{f}'(\hat{\boldsymbol{\beta}}) + \mathbf{H}(\hat{\boldsymbol{\beta}})(\boldsymbol{\beta} - \hat{\boldsymbol{\beta}}) \quad (4)$$

dengan

$\mathbf{f}'(\hat{\boldsymbol{\beta}})$ adalah vektor turunan parsial pertama dari $L^*(\boldsymbol{\beta})$ dihitung pada $\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}$.

$\mathbf{H}(\hat{\boldsymbol{\beta}})$ adalah matriks turunan parsial kedua dari $L^*(\boldsymbol{\beta})$ dihitung pada $\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}$.

Karena $\hat{\boldsymbol{\beta}}$ adalah taksiran maksimum likelihood, maka $\mathbf{f}'(\hat{\boldsymbol{\beta}}) = \mathbf{0}$. Oleh karena

itu (4) menjadi :

$$\mathbf{f}'(\boldsymbol{\beta}) \approx \mathbf{H}(\hat{\boldsymbol{\beta}})(\boldsymbol{\beta} - \hat{\boldsymbol{\beta}}) \quad (5)$$

Jika diasumsikan $[\mathbf{H}(\hat{\boldsymbol{\beta}})]$ tidak singular, maka :

$$\begin{aligned} \mathbf{H}^{-1}(\hat{\boldsymbol{\beta}}) \cdot \mathbf{f}'(\boldsymbol{\beta}) &\approx \mathbf{H}^{-1}(\hat{\boldsymbol{\beta}}) \mathbf{H}(\hat{\boldsymbol{\beta}})(\boldsymbol{\beta} - \hat{\boldsymbol{\beta}}) \\ &\approx \mathbf{I}(\boldsymbol{\beta} - \hat{\boldsymbol{\beta}}) \\ &\approx \boldsymbol{\beta} - \hat{\boldsymbol{\beta}} \end{aligned} \quad (6)$$

$$\hat{\boldsymbol{\beta}} - \boldsymbol{\beta} \approx -[\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} \mathbf{f}'(\boldsymbol{\beta})$$

$$E(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \approx E\left(-[\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} \mathbf{f}'(\boldsymbol{\beta})\right)$$

$$E(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \approx -E\left([\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} \mathbf{f}'(\boldsymbol{\beta})\right) \quad (7)$$

Karena elemen $[\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1}$ merupakan konstanta, maka

$$E(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \approx -E\left([\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} \mathbf{f}'(\boldsymbol{\beta})\right) \text{ menjadi :}$$

$$E(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \approx [\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} E(\mathbf{f}'(\boldsymbol{\beta})) \quad (8)$$

Untuk itu akan dicari :

$$\begin{aligned}
 E(\mathbf{f}'(\boldsymbol{\beta})) &= E \begin{pmatrix} f'_0(\boldsymbol{\beta}) \\ f'_1(\boldsymbol{\beta}) \\ \vdots \\ f'_p(\boldsymbol{\beta}) \end{pmatrix} \\
 &= \begin{pmatrix} E(f'_0(\boldsymbol{\beta})) \\ E(f'_1(\boldsymbol{\beta})) \\ \vdots \\ E(f'_p(\boldsymbol{\beta})) \end{pmatrix}
 \end{aligned} \tag{9}$$

Jika persamaan

$$\begin{aligned}
 f'_u(\boldsymbol{\beta}) &= \frac{\partial L^*(\boldsymbol{\beta})}{\partial \beta_u} \\
 &= \frac{\partial}{\partial \beta_u} \sum_{j=1}^n \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \\
 &= \sum_{j=1}^n \frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} ; u = 0, 1, 2, \dots, p
 \end{aligned}$$

diekspektasikan, maka diperoleh :

$$\begin{aligned}
 E(f'_u(\boldsymbol{\beta})) &= E \left(\sum_{j=1}^n \frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} ; u = 0, 1, 2, \dots, p \right) \\
 &= E \left(\frac{\partial \log f(y_1 | \mathbf{x}_1, \boldsymbol{\beta})}{\partial \beta_u} + \frac{\partial \log f(y_2 | \mathbf{x}_2, \boldsymbol{\beta})}{\partial \beta_u} + \dots + \frac{\partial \log f(y_n | \mathbf{x}_n, \boldsymbol{\beta})}{\partial \beta_u} \right) \\
 &= E \left(\frac{\partial \log f(y_1 | \mathbf{x}_1, \boldsymbol{\beta})}{\partial \beta_u} \right) + E \left(\frac{\partial \log f(y_2 | \mathbf{x}_2, \boldsymbol{\beta})}{\partial \beta_u} \right) + \dots + E \left(\frac{\partial \log f(y_n | \mathbf{x}_n, \boldsymbol{\beta})}{\partial \beta_u} \right)
 \end{aligned}$$

Dengan mencari :

$$E \left(\frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \right) = \sum_{y_j} \frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) : j = 1, 2, \dots, n ; u = 0, 1, 2, \dots, p$$

$$\begin{aligned}
&= \sum_{y_j} \frac{1}{f(y_j | \mathbf{x}_j, \boldsymbol{\beta})} \frac{\partial f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \\
&= \sum_{y_j} \frac{\partial f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \\
&= \frac{\partial}{\partial \beta_u} \sum_{y_j} f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \\
&= \frac{\partial}{\partial \beta_u} 1 \\
&= 0
\end{aligned}$$

diperoleh :

$$E(f'_u(\boldsymbol{\beta})) = 0 + 0 + \dots + 0 = 0 \text{ untuk setiap } u = 0, 1, 2, \dots, p \quad (10)$$

Jadi :

$$E(\mathbf{f}'(\boldsymbol{\beta})) = E \begin{bmatrix} f'_0(\boldsymbol{\beta}) \\ f'_1(\boldsymbol{\beta}) \\ \vdots \\ f'_p(\boldsymbol{\beta}) \end{bmatrix} = \begin{bmatrix} E(f'_0(\boldsymbol{\beta})) \\ E(f'_1(\boldsymbol{\beta})) \\ \vdots \\ E(f'_p(\boldsymbol{\beta})) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \mathbf{0} \quad (11)$$

Dengan mensubstitusikan persamaan di atas ke dalam

$$E(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \approx [\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} E(\mathbf{f}'(\boldsymbol{\beta})), \text{ diperoleh :}$$

$$E(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \approx \mathbf{0}$$

$$E(\hat{\boldsymbol{\beta}}) \approx \boldsymbol{\beta} \quad (12)$$

Oleh karena itu $\text{Var}(\hat{\boldsymbol{\beta}})$ pada (1) menjadi :

$$\text{Var}(\hat{\boldsymbol{\beta}}) = E[(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})^T] \quad (13)$$

Dari (6) diperoleh $\hat{\boldsymbol{\beta}} - \boldsymbol{\beta} \approx -[\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} \mathbf{f}'(\boldsymbol{\beta})$, oleh karena itu (13) menjadi :

$$\begin{aligned}
 \text{Var}(\hat{\boldsymbol{\beta}}) &= E\left[\left(-[\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} \mathbf{f}'(\boldsymbol{\beta})\right)\left(-[\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} \mathbf{f}'(\boldsymbol{\beta})\right)^T\right] \\
 &= E\left[\left([\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1}\right) \mathbf{f}'(\boldsymbol{\beta}) \mathbf{f}'(\boldsymbol{\beta})^T \left([\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1}\right)^T\right] \\
 &= [\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1} E(\mathbf{f}'(\boldsymbol{\beta}) \mathbf{f}'(\boldsymbol{\beta})^T) [\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1}
 \end{aligned} \tag{14}$$

karena matriks $[\mathbf{H}(\hat{\boldsymbol{\beta}})]$ simetris dengan sifat $\left([\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1}\right)^T = \left([\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1}\right)$.

$$\begin{aligned}
 E(\mathbf{f}'(\boldsymbol{\beta}) \mathbf{f}'(\boldsymbol{\beta})^T) &= E\left(\begin{array}{c} f'_0(\boldsymbol{\beta}) \\ f'_1(\boldsymbol{\beta}) \\ \vdots \\ f'_p(\boldsymbol{\beta}) \end{array} \begin{array}{cccc} [f'_0(\boldsymbol{\beta}) & f'_1(\boldsymbol{\beta}) & \dots & f'_p(\boldsymbol{\beta})] \end{array}\right) \\
 &= E\left(\begin{array}{cccc} f'_0(\boldsymbol{\beta})f'_0(\boldsymbol{\beta}) & f'_0(\boldsymbol{\beta})f'_1(\boldsymbol{\beta}) & \dots & f'_0(\boldsymbol{\beta})f'_p(\boldsymbol{\beta}) \\ f'_1(\boldsymbol{\beta})f'_0(\boldsymbol{\beta}) & f'_1(\boldsymbol{\beta})f'_1(\boldsymbol{\beta}) & \dots & f'_1(\boldsymbol{\beta})f'_p(\boldsymbol{\beta}) \\ \vdots & \vdots & \ddots & \vdots \\ f'_p(\boldsymbol{\beta})f'_0(\boldsymbol{\beta}) & f'_p(\boldsymbol{\beta})f'_1(\boldsymbol{\beta}) & \dots & f'_p(\boldsymbol{\beta})f'_p(\boldsymbol{\beta}) \end{array}\right) \\
 &= \left(\begin{array}{cccc} E(f'_0(\boldsymbol{\beta})f'_0(\boldsymbol{\beta})) & E(f'_0(\boldsymbol{\beta})f'_1(\boldsymbol{\beta})) & \dots & E(f'_0(\boldsymbol{\beta})f'_p(\boldsymbol{\beta})) \\ E(f'_1(\boldsymbol{\beta})f'_0(\boldsymbol{\beta})) & E(f'_1(\boldsymbol{\beta})f'_1(\boldsymbol{\beta})) & \dots & E(f'_1(\boldsymbol{\beta})f'_p(\boldsymbol{\beta})) \\ \vdots & \vdots & \ddots & \vdots \\ E(f'_p(\boldsymbol{\beta})f'_0(\boldsymbol{\beta})) & E(f'_p(\boldsymbol{\beta})f'_1(\boldsymbol{\beta})) & \dots & E(f'_p(\boldsymbol{\beta})f'_p(\boldsymbol{\beta})) \end{array}\right)
 \end{aligned} \tag{15}$$

Untuk $u, v=0, 1, \dots, p$ diperoleh :

$$\begin{aligned}
&= \sum_{j=1}^n \left(\sum_{y_j} \left(\left(\frac{\partial}{\partial \beta} \frac{1}{f(y_j | \mathbf{x}_j, \boldsymbol{\beta})} \right) \left(\frac{\partial f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \right) + \frac{1}{f(y_j | \mathbf{x}_j, \boldsymbol{\beta})} \left(\frac{\partial^2 f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u \partial \beta_v} \right) \right) f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \right) + \sum_{U \neq V} E \left(\frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \frac{\partial \log f(y_k | \mathbf{x}_k, \boldsymbol{\beta})}{\partial \beta_v} \right) \\
&= \sum_{j=1}^n \left(- \sum_{y_j} \left(\frac{\partial}{\partial \beta_v} \left(\frac{1}{f(y_j | \mathbf{x}_j, \boldsymbol{\beta})} \frac{\partial f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \right) \right) f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \right) + \sum_{U \neq V} E \left(\frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \frac{\partial \log f(y_k | \mathbf{x}_k, \boldsymbol{\beta})}{\partial \beta_v} \right) \\
&= \sum_{j=1}^n \left(- \sum_{y_j} \left(\frac{\partial}{\partial \beta_v} \left(\frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \right) \right) f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \right) + \sum_{U \neq V} E \left(\frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \frac{\partial \log f(y_k | \mathbf{x}_k, \boldsymbol{\beta})}{\partial \beta_v} \right) \\
&= \sum_{j=1}^n \left(- \sum_{y_j} \left(\frac{\partial^2 \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u \partial \beta_v} \right) f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) \right) + \sum_{U \neq V} E \left(\frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \frac{\partial \log f(y_k | \mathbf{x}_k, \boldsymbol{\beta})}{\partial \beta_v} \right) \\
&= - \sum_j E \left(\frac{\partial^2 \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u \partial \beta_v} \right) f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) + \sum_{U \neq V} E \left(\frac{\partial \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u} \frac{\partial \log f(y_k | \mathbf{x}_k, \boldsymbol{\beta})}{\partial \beta_v} \right)
\end{aligned}$$

karena y_j dan y_k saling bebas, maka :

$$\begin{aligned}
&= - \sum_j E \left(\frac{\partial^2 \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u \partial \beta_v} \right) f(y_j | \mathbf{x}_j, \boldsymbol{\beta}) + 0 \\
&= - E \left(\frac{\partial^2 \sum_{j=1}^n \log f(y_j | \mathbf{x}_j, \boldsymbol{\beta})}{\partial \beta_u \partial \beta_v} \right) \\
&= - E \left(\frac{\partial^2 L^*}{\partial \beta_u \partial \beta_v} \right) \tag{16}
\end{aligned}$$

Oleh karena itu (15) menjadi :

$$E(\mathbf{f}'(\boldsymbol{\beta}) \mathbf{f}'(\boldsymbol{\beta})^T) = - \begin{pmatrix} E \left(\frac{\partial^2 L^*}{\partial \beta_0 \partial \beta_0} \right) & E \left(\frac{\partial^2 L^*}{\partial \beta_0 \partial \beta_1} \right) & \dots & E \left(\frac{\partial^2 L^*}{\partial \beta_0 \partial \beta_p} \right) \\ E \left(\frac{\partial^2 L^*}{\partial \beta_1 \partial \beta_0} \right) & E \left(\frac{\partial^2 L^*}{\partial \beta_1 \partial \beta_1} \right) & \dots & E \left(\frac{\partial^2 L^*}{\partial \beta_1 \partial \beta_p} \right) \\ \vdots & \vdots & \ddots & \vdots \\ E \left(\frac{\partial^2 L^*}{\partial \beta_p \partial \beta_0} \right) & E \left(\frac{\partial^2 L^*}{\partial \beta_p \partial \beta_1} \right) & \dots & E \left(\frac{\partial^2 L^*}{\partial \beta_p \partial \beta_p} \right) \end{pmatrix} = -[\mathbf{H}(\boldsymbol{\beta})]$$

Jadi matriks variansi – kovariansi dari $(\hat{\beta})$ menjadi :

$$\text{Var}(\hat{\beta}) = -[\mathbf{H}(\hat{\beta})]^{-1} \mathbf{H}(\hat{\beta}) [\mathbf{H}(\hat{\beta})]^{-1}.$$

Taksiran matriks variansi – kovariansi dari $(\hat{\beta})$ diberikan oleh :

$$\text{Var}(\hat{\beta}) = -[\mathbf{H}(\hat{\beta})]^{-1} \mathbf{H}(\hat{\beta}) [\mathbf{H}(\hat{\beta})]^{-1}$$

$$\text{Var}(\hat{\beta}) = -[\mathbf{H}(\hat{\beta})]^{-1}$$

Dalam tugas akhir ini, misal $\theta = \begin{bmatrix} \beta \\ \gamma \end{bmatrix} = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_p \\ \gamma_1 \\ \gamma_2 \\ \vdots \\ \gamma_{M-1} \end{bmatrix}$ maka matriks variansi-kovariansi

dari θ memiliki bentuk sebagai berikut :

$$\hat{V}(\hat{\theta}) \approx -[\mathbf{H}(\hat{\theta})]^{-1}$$

$$\approx - \begin{bmatrix} \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_0 \beta_0} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_1 \beta_0} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_2 \beta_0} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_p \beta_0} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_1 \beta_0} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_{M-1} \beta_0} \\ \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_0 \beta_1} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_1 \beta_1} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_2 \beta_1} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_p \beta_1} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_1 \beta_1} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_{M-1} \beta_1} \\ \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_0 \beta_2} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_1 \beta_2} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_2 \beta_2} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_p \beta_2} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_1 \beta_2} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_{M-1} \beta_2} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_0 \beta_p} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_1 \beta_p} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_2 \beta_p} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_p \beta_p} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_1 \beta_p} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_{m-1} \beta_p} \\ \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_0 \gamma_1} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_1 \gamma_1} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_2 \gamma_1} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_p \gamma_1} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_1 \gamma_1} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_{M-1} \gamma_1} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_0 \gamma_{M-1}} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_1 \gamma_{M-1}} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_2 \gamma_{M-1}} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \beta_p \gamma_{M-1}} & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_1 \gamma_{M-1}} & \dots & \frac{\partial^2 L^*(\hat{\theta})}{\partial \gamma_{M-1} \gamma_{M-1}} \end{bmatrix}^{-1}$$

dengan :

$$\frac{\partial^2 L^*}{\partial \beta_u \beta_v} = \sum_{j=1}^n \sum_{k=1}^M Y_{j,k} \left[\frac{(\Phi_{j,k} - \Phi_{j,k-1})(N_{j,k-1} Z_{j,k-1} - N_{j,k} Z_{j,k})}{(\Phi_{j,k} - \Phi_{j,k-1})^2} - \frac{(N_{j,k-1} - N_{j,k})^2}{(\Phi_{j,k} - \Phi_{j,k-1})^2} \right] X_{u,j} X_{v,j}$$

$$\frac{\partial^2 L^*}{\partial \beta_u \gamma_v} = \sum_{j=1}^n \sum_{k=1}^M Y_{j,k} \left[\frac{(\Phi_{j,k} - \Phi_{j,k-1})(N_{j,k} Z_{j,k} \delta_{k,v} - N_{j,k-1} Z_{j,k-1} \delta_{k-1,v})}{(\Phi_{j,k} - \Phi_{j,k-1})^2} - \frac{(N_{j,k-1} - N_{j,k})(N_{j,k} \delta_{k,v} - N_{j,k-1} \delta_{k-1,v})}{(\Phi_{j,k} - \Phi_{j,k-1})^2} \right] X_{u,j}$$

$$\frac{\partial^2 L^*}{\partial \gamma_u \gamma_v} = \sum_{j=1}^n \sum_{k=1}^M Y_{j,k} \left[\frac{(\Phi_{j,k} - \Phi_{j,k-1})(N_{j,k-1} Z_{j,k-1} \delta_{u,k-1} \delta_{v,k-1} - N_{j,k} Z_{j,k} \delta_{u,k} \delta_{v,k})}{(\Phi_{j,k} - \Phi_{j,k-1})^2} - \frac{(N_{j,k} \delta_{u,k} - N_{j,k-1} \delta_{u,k-1})(N_{j,k} \delta_{v,k} - N_{j,k-1} \delta_{v,k-1})}{(\Phi_{j,k} - \Phi_{j,k-1})^2} \right]$$

LAMPIRAN 3

Mencari Distribusi Uji Rasio Likelihood

Uji rasio likelihood digunakan dalam pengujian kegunaan model, dengan hipotesis sebagai berikut :

$$H_0 : \beta_1 = \beta_2 = \dots = \beta_p = 0$$

$$H_1 : \exists \beta_i \neq 0, \text{ untuk } i = 1, 2, \dots, p$$

Definisikan statistik uji Deviance (Hosmer & Lemeshow, 2000 : 13), sebagai berikut :

$$\begin{aligned} D &= -2 \ln \left[\frac{L(\hat{\beta})}{L(\hat{\beta}_{\max})} \right] \\ &= 2 \left[L^*(\hat{\beta}_{\max}) - L^*(\hat{\beta}) \right] \end{aligned}$$

dengan $L^*(\hat{\beta}_{\max})$ adalah nilai dari fungsi log-likelihood untuk model yang jumlah parameternya sama dengan jumlah observasi, yaitu n (*saturated model*), yang dihitung pada $\beta_{\max} = \hat{\beta}_{\max}$ dan $L^*(\hat{\beta})$ adalah nilai fungsi log-likelihood untuk model yang dibentuk yang terdiri dari $p+1$ parameter (*fitted model*), yang dihitung pada $\beta = \hat{\beta}$, dimana $\beta = (\beta_0, \beta_1, \beta_2, \dots, \beta_p)^T$.

Pendekatan deret Taylor orde kedua untuk mencari nilai $L^*(\boldsymbol{\beta})$ di $\boldsymbol{\beta} = \hat{\boldsymbol{\beta}}$

$$\text{adalah : } L^*(\boldsymbol{\beta}) \approx L^*(\hat{\boldsymbol{\beta}}) + (\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})^T \left. \frac{\partial L^*(\boldsymbol{\beta})}{\partial \boldsymbol{\beta}} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} + \frac{1}{2} (\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})^T \left. \frac{\partial^2 L^*(\boldsymbol{\beta})}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} (\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})$$

Diketahui bahwa $-\mathbf{H}(\boldsymbol{\beta}) = -\frac{\partial^2 L^*(\boldsymbol{\beta})}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}^T}$ dan karena $\hat{\boldsymbol{\beta}}$ merupakan taksiran

maximum likelihood maka $\left. \frac{\partial L^*(\boldsymbol{\beta})}{\partial \boldsymbol{\beta}} \right|_{\boldsymbol{\beta}=\hat{\boldsymbol{\beta}}} = \mathbf{0}$. Dengan demikian diperoleh :

$$L^*(\boldsymbol{\beta}) \approx L^*(\hat{\boldsymbol{\beta}}) - \frac{1}{2} (\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})^T [-\mathbf{H}(\hat{\boldsymbol{\beta}})] (\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})$$

$$L^*(\boldsymbol{\beta}) \approx L^*(\hat{\boldsymbol{\beta}}) - \frac{1}{2} (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})^T [-\mathbf{H}(\hat{\boldsymbol{\beta}})] (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})$$

$$\frac{1}{2} (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})^T [-\mathbf{H}(\hat{\boldsymbol{\beta}})] (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \approx L^*(\hat{\boldsymbol{\beta}}) - L^*(\boldsymbol{\beta})$$

Jika n besar maka dengan menggunakan *Central Limit Theorem* diperoleh

bahwa $\frac{(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})}{\sqrt{[-\mathbf{H}(\hat{\boldsymbol{\beta}})]^{-1}}} \sim N(\mathbf{0}, \mathbf{1})$, dan juga diperoleh

$(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})^T [-\mathbf{H}(\hat{\boldsymbol{\beta}})] (\hat{\boldsymbol{\beta}} - \boldsymbol{\beta}) \sim \chi_{p+1}^2$, dengan demikian didapatkan :

$2[L^*(\hat{\boldsymbol{\beta}}) - L^*(\boldsymbol{\beta})] \sim \chi_{p+1}^2$ dimana $p+1$ merupakan jumlah parameter dalam

model.

Dari statistik uji Deviance:

$$D = 2[L^*(\hat{\boldsymbol{\beta}}_{\max}) - L^*(\hat{\boldsymbol{\beta}})]$$

dapat diperoleh :

$$\begin{aligned}
 G &= 2(L^*(\hat{\beta}_{\max}) - L^*(\hat{\beta})) \\
 &= 2\left\{ \left[L^*(\hat{\beta}_{\max}) - L^*(\beta_{\max}) \right] - \left[L^*(\hat{\beta}) - L^*(\beta) \right] + \left[L^*(\beta_{\max}) - L^*(\beta) \right] \right\} \\
 &= 2\left[L^*(\hat{\beta}_{\max}) - L^*(\beta_{\max}) \right] - 2\left[L^*(\hat{\beta}) - L^*(\beta) \right] + 2\left[L^*(\beta_{\max}) - L^*(\beta) \right]
 \end{aligned}$$

Berdasarkan definisi model lengkap dan berdasarkan persamaan :

$$2\left[L^*(\hat{\beta}) - L^*(\beta) \right] \sim \chi^2_{p+1}$$

maka dari persamaan berikut :

$$2\left[L^*(\hat{\beta}_{\max}) - L^*(\beta_{\max}) \right] - 2\left[L^*(\hat{\beta}) - L^*(\beta) \right] + 2\left[L^*(\beta_{\max}) - L^*(\beta) \right]$$

suku pertama pada persamaan diatas mendekati distribusi Chi-Kuadrat dengan derajat bebas n , sedangkan suku kedua mendekati distribusi Chi-Kuadrat dengan derajat bebas $p+1$, dan suku ketiga merupakan suatu konstanta. Konstanta ini akan mendekati nol apabila model model dengan $p+1$ parameter dapat menggambarkan data seperti pada model lengkap.

Dengan demikian :

$$D = 2\left[L^*(\hat{\beta}_{\max}) - L^*(\hat{\beta}) \right] \sim \chi^2_{n-(p+1)}$$

Untuk menguji apakah variabel penjelas secara signifikan mempengaruhi variabel *dependent*, statistik uji Deviance dari model dengan variabel bebas dan statistik uji dari model tanpa menggunakan variabel bebas akan dibandingkan.

Hipotesis sebagai berikut :

$$H_0 : \beta_1 = \beta_2 = \dots = \beta_p = 0$$

$$H_1 : \exists \beta_i \neq 0, \text{ untuk } i = 1, 2, \dots, p$$

Statistik uji :

$$\begin{aligned} G &= D_0 - D_1 \\ &= 2 \left[L^* (\hat{\beta}_{\max}) - L^* (\hat{\beta}_0) \right] - 2 \left[L^* (\hat{\beta}_{\max}) - L^* (\hat{\beta}) \right] \\ &= 2 \left[L^* (\hat{\beta}) - L^* (\beta_0) \right] \end{aligned}$$

dengan D_0 merupakan statistik uji Deviance untuk model tanpa menggunakan variabel penjelas sedangkan D_1 merupakan statistik uji Deviance untuk model dengan menggunakan variabel penjelas.

Dari persamaan :

$$D = 2 \left[L^* (\hat{\beta}_{\max}) - L^* (\hat{\beta}) \right] \sim \lambda_{n-(p+1)}^2$$

diperoleh $D_0 \sim \lambda_{n-(1)}^2$ dan $D_1 \sim \lambda_{n-(p+1)}^2$, dengan demikian :

$$G = 2 \left[L^* (\hat{\beta}) - L^* (\beta_0) \right] \sim \chi_p^2$$

Statistik uji di atas yang akan digunakan untuk pengujian kegunaan model.

LAMPIRAN 4

Program Matlab Metode Newton Raphson Untuk Menaksir Parameter

taksir.m

```
function out = taksir(x, y, b, g, tol)
```

```
clc;
```

```
g = [0 g 100];
```

```
lb = length(b);
```

```
lg = length(g);
```

```
lg1 = lg-2;
```

```
theta = [b g];
```

```
cond = true;
```

```
while(cond)
```

```
    H=calch(x,y,theta(1:lb),theta(lb+1:lb+lg))
```

```
    iH=inv(H)
```

```
    siH=sqrt(-iH)
```

```
    F=zeros(length(theta),1);
```

```
    for m=1:length(theta)-1
```

```
F(m)=calcF(x,y,theta(1:lb),theta(lb+1:lb+lg),m);
```

```
end
```

```
F = F';
```

```
F = [F(1:lb) F(lb+2:(lb+lg)-1)];
```

```
F = F';
```

```
theta1 = [theta(1:lb) theta(lb+2:(lb+lg)-1)];
```

```
theta2=(theta1'-(iH*F))';
```

```
cond = norm(abs(theta1 - theta2)) > tol;
```

```
theta =[theta2(1:lb) 0 theta2(lb+1:(lb+lg)) 100];
```

```
disp(theta2);
```

```
end
```

```
out = theta2;
```

calcH.m

```
function H = calcH(x,y,b,g)
```

```
[j1 k1] = size(y);
```

```
H = zeros(length([b g])-2);
```

```
for j=1:j1
```

```
    for k=1:k1
```

```

for m=1:length([b g])-2
    for n=m:length([b g])-2
        if m<=length(b) & n<=length(b)
            %beta beta
            u=m-1;
            v=n-1;
            %disp([j k m n]);
            H(m,n) = H(m,n) + (y(j,k)*(((psi1(x,j,k,b,g)-psi1(x,j,k-1,b,g)) *
(en(x,j,k-1,b,g)*zet(x,j,k-1,b,g)- en(x,j,k,b,g)*zet(x,j,k,b,g)) / ( ( psi1(x,j,k,b,g)-
psi1(x,j,k-1,b,g) )^2 ))-(( ( en(x,j,k-1,b,g)-en(x,j,k,b,g))^2 )/( ( psi1(x,j,k,b,g)-
psi1(x,j,k-1,b,g) )^2 ))) * x(u+1,j) * x(v+1,j)));
        elseif m>length(b) & n>length(b)
            %gamma gamma
            u=m-length(b);
            v=n-length(b);
            H(m,n) = H(m,n) + (y(j,k) * (((psi1(x,j,k,b,g)-psi1(x,j,k-
1,b,g))* (en(x,j,k-1,b,g)*zet(x,j,k-1,b,g)*delta(u,k-1)*delta(v,k-1) -
en(x,j,k,b,g)*zet(x,j,k,b,g)*delta(u,k)*delta(v,k))/((psi1(x,j,k,b,g)-psi1(x,j,k-
1,b,g))^2))-(((en(x,j,k,b,g)*delta(u,k)-en(x,j,k-1,b,g)*delta(u,k-
1))* (en(x,j,k,b,g)*delta(v,k)-en(x,j,k-1,b,g)*delta(v,k-1)))/((psi1(x,j,k,b,g)-
psi1(x,j,k-1,b,g))^2))));
        else

```

```

%beta gamma / gamma beta

u=m-1;

v=n-length(b);

H(m,n) = H(m,n) +(y(j,k) * (((psi1(x,j,k,b,g)-psi1(x,j,k-
1,b,g))*(en(x,j,k,b,g)*zet(x,j,k,b,g)*delta(v,k)-en(x,j,k-1,b,g)*zet(x,j,k-
1,b,g)*delta(v,k-1)))/((psi1(x,j,k,b,g)-psi1(x,j,k-1,b,g))^2))-(((en(x,j,k-1,b,g)-
en(x,j,k,b,g))*(en(x,j,k,b,g)*delta(v,k)-en(x,j,k-1,b,g)*delta(v,k-
1)))/((psi1(x,j,k,b,g)-psi1(x,j,k-1,b,g))^2))) * x(u+1,j));

end
end
end
end
end

for m=1:length([b g])-2
    for n=m+1:length([b g])-2
        H(n,m)=H(m,n);
    end
end
end

```

calcF.m

```
function out = calcF(x,y,b,g,m)
```

```
[j1 k1] = size(y);
```

```
out=0;
```

```
for j=1:j1
```

```
    %disp(j);
```

```
    for k=1:k1
```

```
        %disp(k);
```

```
        if m<=length(b)
```

```
            %beta
```

```
            u=m-1;
```

```
            out = out + (y(j,k) * ((en(x,j,k-1,b,g)-en(x,j,k,b,g))/(psi1(x,j,k,b,g)-psi1(x,j,k-1,b,g))) * x(u+1,j));
```

```
        else
```

```
            %gamma
```

```
            u=m-length(b)-1;
```

```
            out = out + (y(j,k) * ((en(x,j,k,b,g)*delta(u,k)-en(x,j,k-1,b,g)*delta(u,k-1))/(psi1(x,j,k,b,g)-psi1(x,j,k-1,b,g))));
```

```
        end
```

```
    end
```

```
end
```

psi1.m

```
function out = psi1(x, j, k, b, g)
```

```
out = ((1/2) * (1+erf(zet(x, j, k, b, g)/sqrt(2))));
```

en.m

```
function out = en(x, j, k, b, g)
```

```
out = ((1/sqrt(2*pi)) * exp(-(zet(x, j, k, b, g)^2)/2));
```

delta.m

```
function out = delta(i, j)
```

```
if(i==j)
```

```
    out = 1;
```

```
else
```

```
    out = 0;
```

```
end
```

zet.m

```
function out = zet(x, j, k, b, g);
```

```
out = g(k+1) - (b(1)*x(1,j) + b(2)*x(2,j) + b(3)*x(3,j));
```

