

LISTING PROGRAM PERKALIAN MATRIKS  
DENGAN MPICH2

```

/* -----
----- */
/* -- Parallel Matrix Operations - Matrix Multiplication
-- */
/* --
-- */
/* -- E. van den Berg
02/10/2001 -- */
/* -----
----- */

#include "mpi.h"
#include <stdio.h>
#include <stdlib.h>

#define TAG_MATRIX_PARTITION 0x4560

// Type definitions
typedef struct
{ unsigned int    m, n; // Rows, cols
  double         *data; // Data, ordered by row, then by col
  double         **rows; // Pointers to rows in data
} TMatrix;

// Global variables
int processor_rank = 0;
int processor_count = 1;

// Function declarations
TMatrix createMatrix (const unsigned int rows, const unsigned
int cols);
void freeMatrix (TMatrix *matrix);
int validMatrix (TMatrix matrix);
TMatrix initMatrix (void);
TMatrix matrixMultiply (TMatrix A, TMatrix B);
void doMatrixMultiply (TMatrix A, TMatrix B, TMatrix C);
void printMatrix (TMatrix A);

/* -----
----- */
int main (int argc, char *argv[])
/* -----
----- */
{ MPI_Status status;
  TMatrix A,B,C,D;
  unsigned int m, n, i, j, offset;
  double time0, time1;

  A = initMatrix(); B = initMatrix(); C = initMatrix(); D =
initMatrix();

  // Always use MPI_Init first

```

```

if (MPI_Init(&argc, &argv) == MPI_SUCCESS) do
{ // Determine which number is assigned to this processor
  MPI_Comm_size (MPI_COMM_WORLD, &processor_count);
  MPI_Comm_rank (MPI_COMM_WORLD, &processor_rank );

  if (processor_rank == 0)
  { printf ("Please enter matrix dimension n : ");
scanf("%u", &n);

    // Record starting time
    time0 = MPI_Wtime();

    // Allocate memory for matrices
    A = createMatrix(n, n);
    B = createMatrix(n, n);
    C = createMatrix(n, n);

    // Initialize matrices
    for (i = 0; i < n ; i++)
    { for (j = 0; j < n; j++)
      { A.rows[i][j] = (int)(3.0 * (rand() / (RAND_MAX +
1.0)));
        B.rows[i][j] = (int)(3.0 * (rand() / (RAND_MAX +
1.0)));
      }
    }
    if (!validMatrix(A) || !validMatrix(B) || !validMatrix(C))
n = 0;

    // Broadcast (send) size of matrix
    MPI_Bcast((void *)&n, 1, MPI_INT, 0, MPI_COMM_WORLD); if
(n == 0) break;
    m = n / processor_count;

    // Broadcast (send) B matrix
    MPI_Bcast((void *)B.data, n*n, MPI_DOUBLE, 0,
MPI_COMM_WORLD);

    // Send each process it's own part of A
    offset = n - m * (processor_count - 1);
    for (i = 1; i < processor_count; i++)
    { MPI_Send((void *)A.rows[offset], m*n, MPI_DOUBLE,
i, TAG_MATRIX_PARTITION, MPI_COMM_WORLD);
      offset += m;
    }

    // Multiply own part of matrix A with B into already
existing matrix C
    A.m = n - m * (processor_count - 1);
    doMatrixMultiply(A,B,C);
    A.m = n;

    // Receive part of C matrix from each process
    offset = n - m * (processor_count - 1);
    for (i = 1; i < processor_count; i++)
    { MPI_Recv((void *)C.rows[offset], m*n, MPI_DOUBLE,
i, TAG_MATRIX_PARTITION, MPI_COMM_WORLD,
&status);
      offset += m;

```

```

    }

    // Record finish time
    time1 = MPI_Wtime();

    // Print time statistics
    printf ("Total time using [%2d] processors : [%f]
seconds\n", processor_count, time1 - time0);

}
else
{
    // Broadcast (receive) size of matrix
    MPI_Bcast((void *)&n, 1, MPI_INT, 0, MPI_COMM_WORLD); if
(n == 0) break;

    // Allocate memory for matrices
    m = n / processor_count;
    A = createMatrix(m, n);
    B = createMatrix(n ,n);

    // Broadcast (receive) B matrix
    MPI_Bcast((void *)B.data, n*n, MPI_DOUBLE, 0,
MPI_COMM_WORLD);
    MPI_Recv((void *)A.data, m*n, MPI_DOUBLE, 0,
TAG_MATRIX_PARTITION, MPI_COMM_WORLD, &status);

    // Multiply local matrices
    C = matrixMultiply(A,B);

    // Send back result
    MPI_Send((void *)C.data, m*n, MPI_DOUBLE, 0,
TAG_MATRIX_PARTITION, MPI_COMM_WORLD);
}
} while (0); // Enable break statement to be used above

// Free matrix data
freeMatrix(&A); freeMatrix(&B); freeMatrix(&C);

// Wait for everyone to stop
MPI_Barrier(MPI_COMM_WORLD);

// Always use MPI_Finalize as the last instruction of the
program
MPI_Finalize();

return 0;
}

/* -----
----- */
TMatrix createMatrix(const unsigned int rows, const unsigned int
cols)
/* -----
----- */
{ TMatrix      matrix;
  unsigned long int m, n;
  unsigned int   i;

```

```

    m = rows; n = cols;
    matrix.m   = rows;
    matrix.n   = cols;
    matrix.data = (double *) malloc(sizeof(double) * m * n);
    matrix.rows = (double **) malloc(sizeof(double *) * m);
    if (validMatrix(matrix))
    {
        matrix.m = rows;
        matrix.n = cols;
        for (i = 0; i < rows; i++)
        {
            matrix.rows[i] = matrix.data + (i * cols);
        }
    }
    else
    {
        freeMatrix(&matrix);
    }

    return matrix;
}

/* -----
----- */
void freeMatrix (TMatrix *matrix)
/* -----
----- */
{
    if (matrix == NULL) return;

    if (matrix -> data) { free(matrix -> data); matrix -> data =
NULL; }
    if (matrix -> rows) { free(matrix -> rows); matrix -> rows =
NULL; }
    matrix -> m = 0;
    matrix -> n = 0;
}

/* -----
----- */
int validMatrix (TMatrix matrix)
/* -----
----- */
{
    if ((matrix.data == NULL) || (matrix.rows == NULL) ||
        (matrix.m == 0) || (matrix.n == 0))
        return 0;
    else return 1;
}

/* -----
----- */
TMatrix initMatrix()
/* -----
----- */
{
    TMatrix matrix;

    matrix.m = 0;
    matrix.n = 0;
    matrix.data = NULL;
    matrix.rows = NULL;
}

```

```

    return matrix;
}

/* -----
----- */
TMatrix matrixMultiply(TMatrix A, TMatrix B)
/* -----
----- */
{ TMatrix C;

  C = initMatrix();

  if (validMatrix(A) && validMatrix(B) && (A.n == B.m))
  { C = createMatrix(A.m, B.n);
    if (validMatrix(C))
    { doMatrixMultiply(A, B, C);
    }
  }

  return C;
}

/* -----
----- */
void doMatrixMultiply(TMatrix A, TMatrix B, TMatrix C)
/* -----
----- */
{ unsigned int i, j, k;
  double sum;

  for (i = 0; i < A.m; i++) // Rows
  { for (j = 0; j < B.n; j++) // Cols
    { sum = 0;
      for (k = 0; k < A.n; k++) sum += A.rows[i][k] *
B.rows[k][j];
      C.rows[i][j] = sum;
    }
  }
}

/* -----
----- */
void printMatrix(TMatrix A)
/* -----
----- */
{ unsigned int i, j;

  if (validMatrix(A))
  { for (i = 0; i < A.m; i++)
    { for (j = 0; j < A.n; j++) printf ("%7.3f ",
A.rows[i][j]);
      printf ("\n");
    }
  }
}

```

LISTING PROGRAM PERKALIAN MATRIKS  
DENGAN CILK++

```

/*
 * matrix-mulitpy.cilk
 *
 * First of five matrix multiply examples to compare dense matrix
multiplication
 * algorithms using Cilk parallelization.
 * Example 1: Straightforward loop parallelization of matrix
multiplication.
 *
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 *
 */

#include <cilk.h>
#include <cilkview.h>
#include <iostream>

#define DEFAULT_MATRIX_SIZE 4

// Multiply double precision square n x n matrices. A = B * C
// Matrices are stored in row major order.
// A is assumed to be initialized.
void matrix_multiply(double* A, double* B, double* C, unsigned int
n)
{
    if (n < 1) {
        return;
    }

```

```

    cilk_for(unsigned int i = 0; i < n; ++i) {
        // This is the only Cilk++ keyword used in this program
        // Note the order of the loops and the code motion of
the i * n and k * n
        // computation. This gives a 5-10 performance
improvement over exchanging
        // the j and k loops.
        int itn = i * n;
        for (unsigned int k = 0; k < n; ++k) {
            for (unsigned int j = 0; j < n; ++j) {
                int ktn = k * n;
                // Compute A[i,j] in the inner loop.
                A[itn + j] += B[itn + k] * C[ktn + j];
            }
        }
    }
    return;
}

void print_matrix(double* M, int nn)
{
    for (int i = 0; i < nn; ++i) {
        for (int j = 0; j < nn; ++j) {
            std::cout << M[i * nn + j] << ", ";
        }
        std::cout << std::endl;
    }
    return;
}

int cilk_main(int argc, char** argv) {
    // Create random input matrices. Override the default size
with argv[1]
    // Warning: Matrix indexing is 0 based.
    int nn = DEFAULT_MATRIX_SIZE;
    if (argc > 1) {
        nn = std::atoi(argv[1]);
    }

    std::cout << "Simple algorithm: Mulitply two " << nn << " by "
<< nn
        << " matrices, coumputing A = B*C" << std::endl;

    double* A = (double*) calloc(nn* nn, sizeof(double));
    double* B = (double*) calloc(nn* nn, sizeof(double));
    double* C = (double*) calloc(nn* nn, sizeof(double));
    if (NULL == A || NULL == B || NULL == C) {
        std::cout << "Fatal Error. Cannot allocate matrices A, B,
and C."
            << std::endl;
        return 1;
    }

    // Populate B and C pseudo-randomly -
    // The matrices are populated with random numbers in the range
(-1.0, +1.0)
    cilk_for(int i = 0; i < nn * nn; ++i) {
        B[i] = (float) ((i * i) % 1024 - 512) / 512;
    }
}

```

```

cilk_for(int i = 0; i < nn * nn; ++i) {
    C[i] = (float) (((i + 1) * i) % 1024 - 512) / 512;
}

// Multiply to get A = B*C
cilk::cilkview cv;
cv.reset();
cv.start();
matrix_multiply(A, B, C, (unsigned int)nn);
cv.stop();
float par_time = cv.accumulated_milliseconds() / 1000.f;
std::cout << " Matrix Multiply took " << par_time << "
seconds."
    << std::endl;

// If n is small, print the results
if (nn <= 8) {
    std::cout << "Matrix A:" << std::endl;
    print_matrix(B, nn);
    std::cout << std::endl << "Matrix B:" << std::endl;
    print_matrix(C, nn);
    std::cout << std::endl << "Matrix C = A * B:" <<
std::endl;
    print_matrix(A, nn);
}

free(A);
free(B);
free(C);
return 0;
}

```



LISTING PROGRAM *SORTING* DENGAN M PICH2

```

/* -----
----- */
/* -- Parallel Binary Sorting Example
-- */
/* --
-- */
/* -- E. van den Berg
01/10/2001 -- */
/* -----
----- */

#include <stdio.h>
#include <stdlib.h>
#include "mpi.h"

#define TAG_HEADER          0x1234
#define TAG_DATA            0x1235
#define TAG_SORTED_DATA    0x1236

// Type definitions
typedef struct
{
    int      processor_rank;
    int      processor_count;
    int      processor_owner;
    int      *data;
    long int  offset;
    long int  size;
} TParallelSortHeader;

// Global variables
int processor_rank = 0;
int processor_count = 1;

// Function declarations
void parallelBinarySort (int *data, long int size);
void doParallelBinarySort (TParallelSortHeader headerA, int
hasOwner);
void divideWork          (TParallelSortHeader *headerA,
TParallelSortHeader *headerB);
void merge                (int *sortedA, long int sizeA, int
*sortedB, long int sizeB);
void sequentialBinarySort (int *data, long int size);

/* -----
----- */
int main (int argc, char *argv[])
/* -----
----- */
{
    double    time0, time1;
    long int  size, i;

```

```

int      *data = NULL;

// Always use MPI_Init first
if (MPI_Init(&argc, &argv) == MPI_SUCCESS)
{ // Determine which number is assigned to this processor
  MPI_Comm_size (MPI_COMM_WORLD, &processor_count);
  MPI_Comm_rank (MPI_COMM_WORLD, &processor_rank );

  if (processor_rank == 0)
  { // Read data
    printf ("Number of elements : "); scanf("%lu", &size);

    // Fill data array with random numbers
    data = (int *) malloc (sizeof(int) * size);
    for (i = 0; i < size; i++) data[i] = (int)(3000.0 *
(rand() / (RAND_MAX + 1.0)));
  }

  time0 = MPI_Wtime();
  {
    parallelBinarySort(data, size);
  }
  time1 = MPI_Wtime();

  if (processor_rank == 0)
  {
    printf ("Total time : %f seconds\n", time1 - time0);
  }
}

// Wait for every process to finish
MPI_Barrier(MPI_COMM_WORLD);

// Always use MPI_Finalize as the last MPI instruction of the
program!
MPI_Finalize();

return 0;
}

```

```

/* -----
----- */
void parallelBinarySort (int *data, long int size)
/* -----
----- */
{ TParallelSortHeader headerA;
  MPI_Status          status;

  if (processor_rank == 0)
  { if (data == NULL) size = 1;
    headerA.processor_rank = 0;
    headerA.processor_count = processor_count;
    headerA.processor_owner = -1;
    headerA.data             = NULL;
    headerA.size             = 0;
    headerA.offset           = 0;

```

```

        // Send bogus header message to all processor that will not
        // be used
        // due to a shortage of data items. Otherwise the processors
        // would wait for a header message forever.
        while (headerA.processor_count > size)
        { headerA.processor_count --;
          MPI_Send((void *)&headerA, sizeof(headerA), MPI_BYTE,
                  headerA.processor_count, TAG_HEADER,
MPI_COMM_WORLD);
        }

        // Set data array field
        if (data == NULL) return;
        headerA.data = data;
        headerA.size = size;

        // Initiate real parallel sort routine
        doParallelBinarySort (headerA, 0);
    }
    else
    {
        // Receive header
        MPI_Recv((void *)&headerA, sizeof(headerA), MPI_BYTE,
                MPI_ANY_SOURCE, TAG_HEADER, MPI_COMM_WORLD,
&status);

        // If no elements will be sent to this process, cancel for
        // this process.
        if (headerA.size == 0) { printf ("%d] Cancelled.\n",
processor_rank); return; }

        // This malloc might fail and solving it in this case
        // would require sending a message to the 'parent' to
        // indicate that the operation be cancelled. If we just
        // exit here, then the other processor will be hanging,
        // waiting for the message to be received.
        headerA.data = (int *) malloc (sizeof(int) * headerA.size);

        // Receive the data to be sorted
        MPI_Recv((void *)headerA.data, headerA.size, MPI_INT,
                headerA.processor_owner, TAG_DATA, MPI_COMM_WORLD,
&status);

        // Initiate real parallel sort routine
        doParallelBinarySort (headerA, 1);
    }
}

/* -----
----- */
void doParallelBinarySort (TParallelSortHeader headerA, int
hasOwner)
/* -----
----- */
{ TParallelSortHeader headerB;
  MPI_Status          status;
  int                  *dataB;

```

```

// Divide work specified by header
divideWork (&headerA, &headerB);

// Send data to other process
if (headerB.size > 0)
{ // Set data field in headerB to NULL and send header
  // to prevent it from being used directly by the other
  // process. Not really necessary but prevents difficult
  // to find bugs.
  dataB = headerB.data; headerB.data = NULL;
  MPI_Send((void *)&headerB, sizeof(headerB), MPI_BYTE,
           headerB.processor_rank,
           TAG_HEADER, MPI_COMM_WORLD);

  // Restore data field in headerB and send data
  headerB.data = dataB;
  MPI_Send((void *)headerB.data, headerB.size, MPI_INT,
           headerB.processor_rank,
           TAG_DATA, MPI_COMM_WORLD);
}

// Split data if there is (A) sufficient data, and (B)
processors available.
// Otherwise just initiate sequential binary sort within this
process.
if ((headerA.size > 1) && (headerA.processor_count > 1))
{ doParallelBinarySort(headerA, 0);
}
else
{ sequentialBinarySort(headerA.data, headerA.size);
}

// Data provided by headerA has now been sorted. If any
expected,
// receive data as specified by headerB.
if (headerB.size > 0)
{ MPI_Recv((void *)headerB.data, headerB.size, MPI_INT,
           headerB.processor_rank,
           TAG_SORTED_DATA, MPI_COMM_WORLD, &status);
}

// Merge results
merge(headerA.data, headerA.size, headerB.data, headerB.size);

// Send back result if has owner and free memory
if (hasOwner)
{ MPI_Send((void *)headerA.data, headerA.size + headerB.size,
MPI_INT,
           headerA.processor_owner,
           TAG_SORTED_DATA, MPI_COMM_WORLD);

  // Free allocated memory
  free(headerA.data);
}
}

```

```

/* -----
----- */
void divideWork (TParallelSortHeader *headerA, TParallelSortHeader
*headerB)
/* -----
----- */
{ int countA, countB, sizeA, sizeB;

// Is there a processor available to divide work to
if (headerA -> processor_count > 1)
{
    countA = headerA -> processor_count / 2;
    countB = headerA -> processor_count - countA;
    sizeA = (int)(((headerA -> size) / (double)(countA +
countB)) * countA);
    sizeB = headerA -> size - sizeA;
    headerA -> processor_count = countA;
    headerA -> size = sizeA;
    headerB -> processor_rank = headerA -> processor_rank +
countA;
    headerB -> processor_count = countB;
    headerB -> processor_owner = headerA -> processor_rank;
    headerB -> data = headerA -> data + sizeA;
    headerB -> size = sizeB;
    headerB -> offset = headerA -> offset + sizeA;
}
else
{
    headerB -> processor_rank = -1;
    headerB -> processor_count = -1;
    headerB -> processor_owner = -1;
    headerB -> data = NULL;
    headerB -> size = 0;
    headerB -> offset = -1;
}
}

/* -----
----- */
void merge (int *sortedA, long int sizeA, int *sortedB, long int
sizeB)
/* -----
----- */
{ int *sortedC, sizeC;
  long int i = 0, j = 0, k = 0;

// Allocate memory for temporary array
sizeC = sizeA + sizeB;
sortedC = (int *) malloc (sizeof(int) * sizeC);

// If memory allocation for temporary result array successful,
// start merging. After merging into C, the results will be
// written back to A and B.
if (sortedC)
{
    // While not at the end of one of the sequences, determine
the

```

```

// smaller element of the two currently pointed-to elements
in
// the sequences and copy this element into sequence C.
while ((i < sizeA) && (j < sizeB))
{ if ((sortedA)[i] <= (sortedB)[j])
    sortedC[k++] = (sortedA)[i++];
  else sortedC[k++] = (sortedB)[j++];
}

// While not at the end of A, copy remaining elements to C.
while (i < sizeA) sortedC[k++] = (sortedA)[i++];

// While not at the end of B, copy remaining elements to C.
while (j < sizeB) sortedC[k++] = (sortedB)[j++];

// Copy back the first half of C into A, and second half to
B.
// The halves are determined by the number of elements in A
and B.
k = 0;
for (i = 0; i < sizeA; i++) sortedA[i] = sortedC[k++];
for (j = 0; j < sizeB; j++) sortedB[j] = sortedC[k++];

// Free memory for temporary array
free(sortedC);
}

/* -----
----- */
void sequentialBinarySort (int *data, long int size)
/* -----
----- */
{ int *dataA, *dataB;
  long int sizeA, sizeB;

  if (size > 1)
  { dataA = data;
    sizeA = size / 2;
    dataB = data + sizeA;
    sizeB = size - sizeA;
    sequentialBinarySort(dataA, sizeA);
    sequentialBinarySort(dataB, sizeB);
    merge(dataA, sizeA, dataB, sizeB);
  }
}

```

## Lampiran IV

LISTING PROGRAM *SORTING* DENGAN CILK++

```

// -*- C++ -*-
/*
 * qsort.cilk
 *
 * An implementation of quicksort using Cilk parallelization.
 *
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 * possibility of such damages, whether in an action of contract,
 * negligence, tort, or otherwise.
 *
 */
#include <cilk.h>
#include <cilkview.h>
#include <algorithm>
#include <iostream>
#include <iterator>
#include <functional>

// Sort the range between bidirectional iterators begin and end.
// end is one past the final element in the range.
// Use the Quick Sort algorithm, using recursive divide and
conquer.
// This function is NOT the same as the Standard C Library qsort()
function.
// This implementation is pure C++ code before Cilk++ conversion.

void sample_qsort(int * begin, int * end)
{
    if (begin != end) {
        --end; // Exclude last element (pivot) from partition
        int * middle = std::partition(begin, end,
                                     std::bind2nd(std::less<int>(), *end));
    }
}

```

```

        using std::swap;
        swap(*end, *middle); // move pivot to middle
        cilk_spawn sample_qsorth(begin, middle);
        sample_qsorth(++middle, ++end); // Exclude pivot and
restore end
        cilk_sync;
    }
}

// A simple test harness
int qmain(int n)
{
    int* a = new int[n];
    cilk::cilkview cv;

    for (int i = 0; i < n; ++i)
        a[i] = i;
    std::random_shuffle(a, a + n);
    std::cout << "Sorting " << n << " integers" << std::endl;
    cv.start();
    sample_qsorth(a, a + n);
    cv.stop();
    cv.dump("qsorth-results", false);

    std::cout << cv.accumulated_milliseconds() / 1000.f << "
seconds" << std::endl;

    // Confirm that a is sorted and that each element contains the
index.
    for (int i = 0; i < n - 1; ++i) {
        if (a[i] >= a[i + 1] || a[i] != i) {
            std::cout << "Sort failed at location i=" << i << "
a[i] = "
                << a[i] << " a[i+1] = " << a[i + 1] <<
std::endl;
            delete[] a;
            return 1;
        }
    }
    std::cout << "Sort succeeded." << std::endl;
    delete[] a;
    return 0;
}

int cilk_main(int argc, char* argv[])
{
    int n = 10 * 1000 * 1000;
    if (argc > 1) {
        n = std::atoi(argv[1]);
        if (n <= 0) {
            std::cerr << "Invalid argument" << std::endl;
            std::cerr << "Usage: qsorth N" << std::endl;
            std::cerr << "          N = number of elements to sort"
<< std::endl;
            return 1;
        }
    }
    return qmain(n);
}

```