

Judul:

Sistem kendali kapal-pengejar-nirawak berbasis neural networks menggunakan ensemble kalman filter sebagai prediktor informasi radar = Neural networks control system for autonomous chaser boat using ensemble kalman filter for predicting its positions based on radar information

Pengarang/Penulis:

Karlisa Priandana, author

Subjek:

Neural networks (Computer science); Autonomous underwater vehicles; Radar -- Installation on ships

Nomor Panggil:

D2334

Penerbitan:

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