

**Judul:**

Sistem kendali autonomous hexacopter heavy-lift berbasis elman recurrent neural network dan unjuk kerjanya terhadap gangguan impulsif =  
Autonomous control system of heavy lift hexacopter based elman recurrent neural network and its performance to impulsive disturbance

**Pengarang/Penulis:**

Bhakti Yudho Suprpto, author

**Subjek:**

Neural networks (Computer science)--Technological innovations

**Nomor Panggil:**

D2400

**Penerbitan:**

**Link Terkait:**

- [Deskripsi Bibliografi](#)
- [Abstrak](#)
- [Dokumen Yang Mirip](#)
- [Universitas Indonesia Library](#)