

Judul:

Simulasi dan analisis efektivitas path planning berbasis artificial potential field dengan algoritma virtual obstacle, artificial goals, dan goal based potential field = Simulations and analysis of path planning based on artificial potential field using virtual obstacle, artificial goals, and goal based potential field

Pengarang/Penulis:

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Subjek:

Robotics; Robot control

Nomor Panggil:

S-pdf

Penerbitan:

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