

Judul:

Desain dan Analisis Pengembangan Sistem Kendali Otonom Quadcopter dalam Simulator Gazebo Menggunakan Metode Direct Inverse Control Berbasis Deep Neural Network dan Long-Short Term Memory = Design and Development Analysis of Autonomous Quadcopter Control System in Gazebo Simulator Using Direct Inverse Control Method Based on Deep Neural Network and Long-Short Term Memory

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Robots -- Control systems

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